

# Toward Simulated Students for Reinforcement Learning-Driven Tutorial Planning in GIFT

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the **intelliMEDIA**  
group

# Tutorial Planning

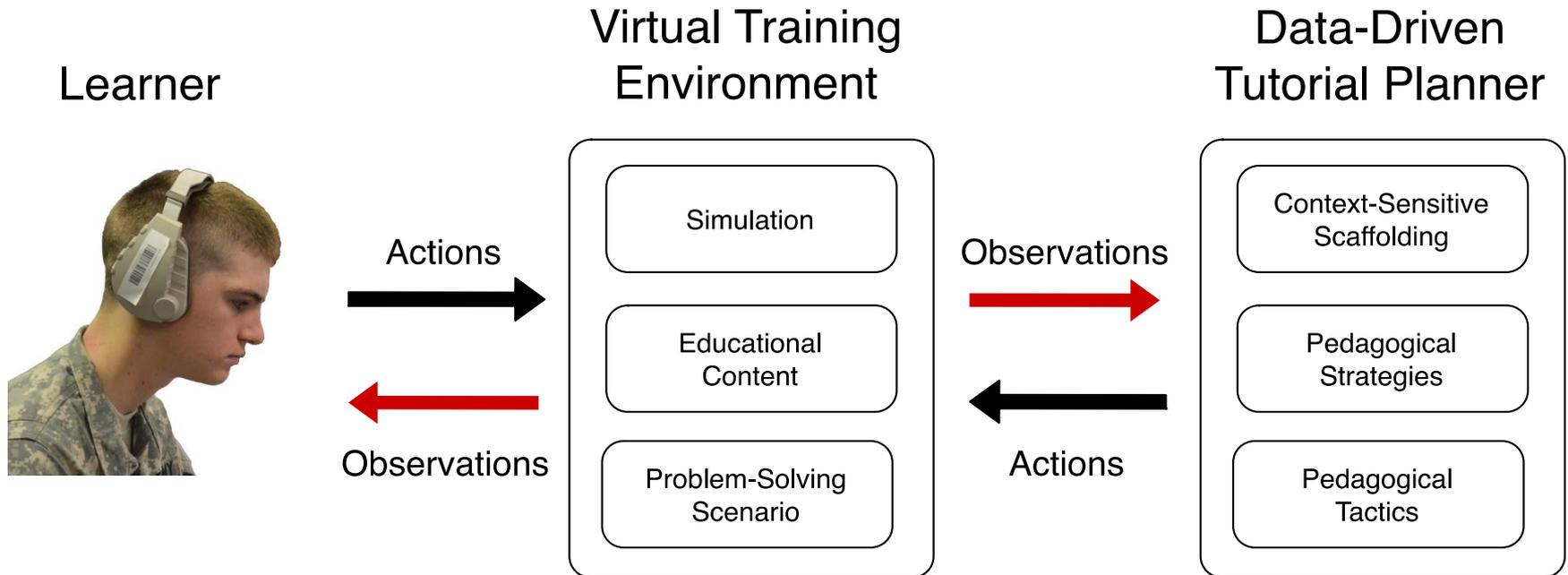


# Tutorial Planning



- Hints
- Feedback
- Scenario adaptations
- Embedded assessments
- Remedial instruction

# Data-Driven Tutorial Planning



# Data-Driven Tutorial Planning

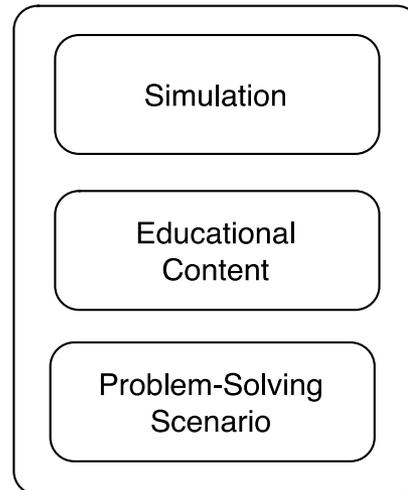


Simulated Student



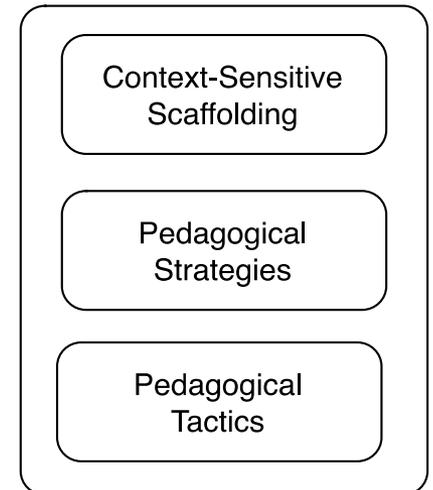
Actions  
Observations

Virtual Training Environment

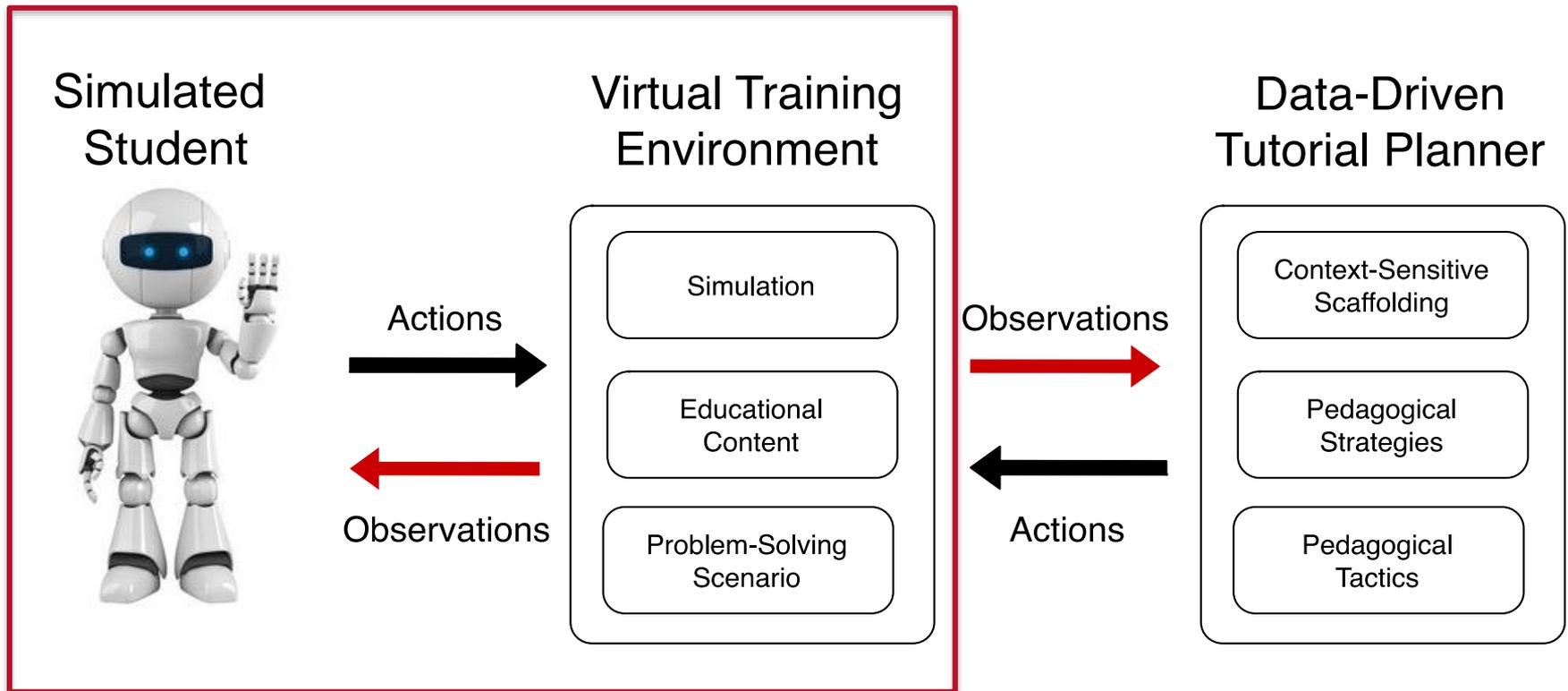


Observations  
Actions

Data-Driven Tutorial Planner



# Data-Driven Tutorial Planning



# Research Question



How can we leverage *simulated students* to generate synthetic data for training generalized tutorial planners in GIFT?

# Outline



- Reinforcement Learning-Based Tutorial Planning
- Design Issues for Simulated Students
- Implementing Simulated Students for COIN Training
- Conclusions and Future Directions

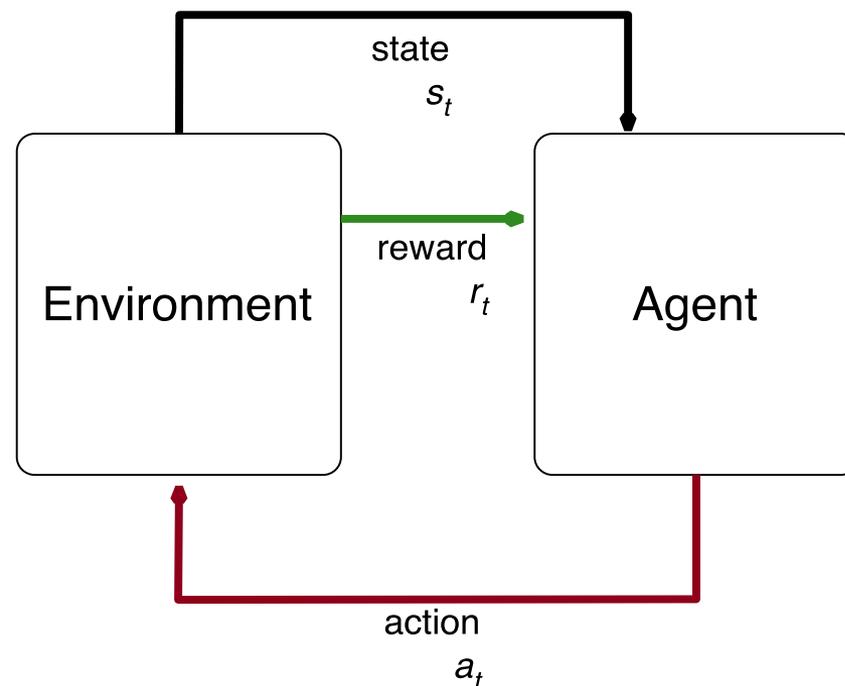
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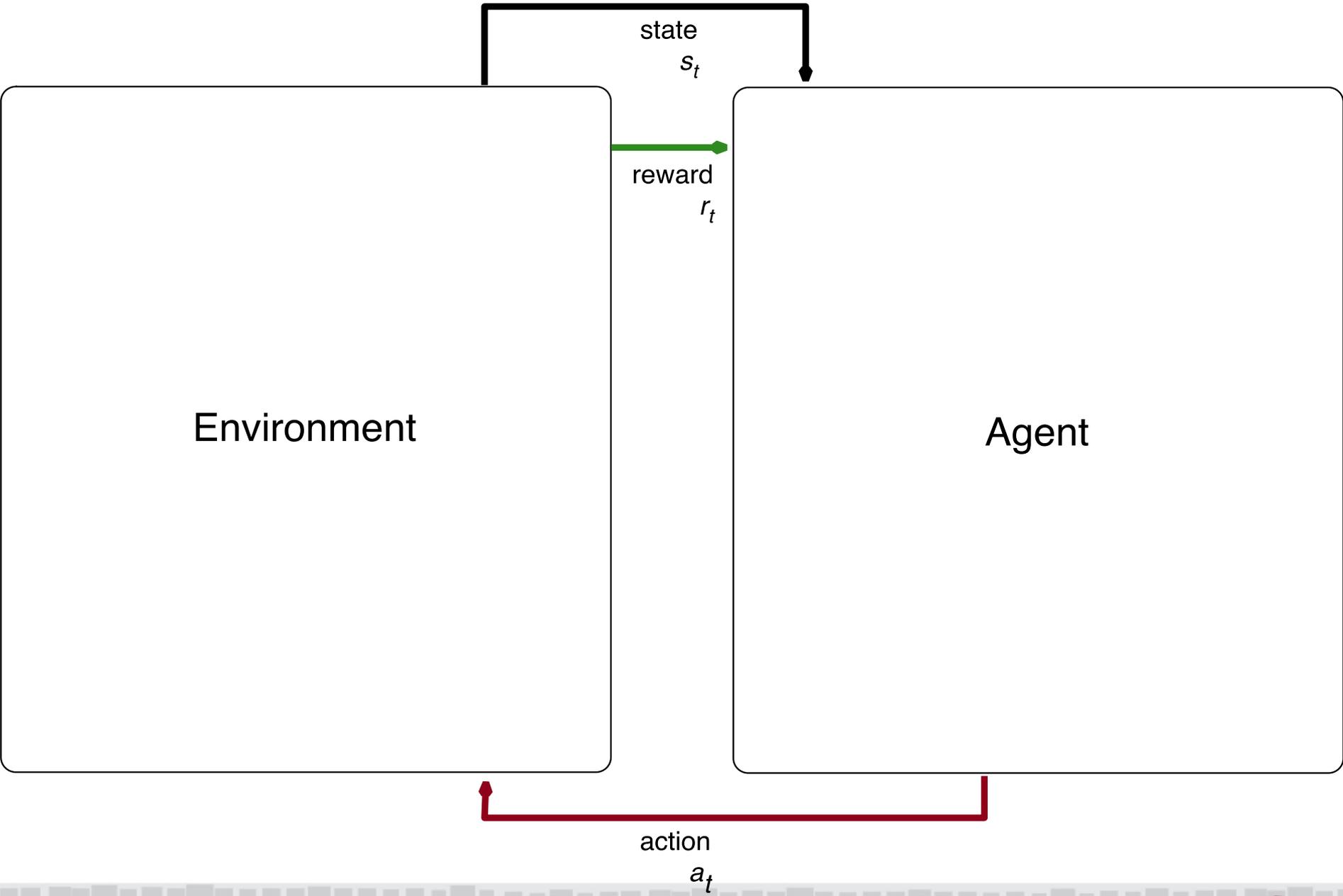
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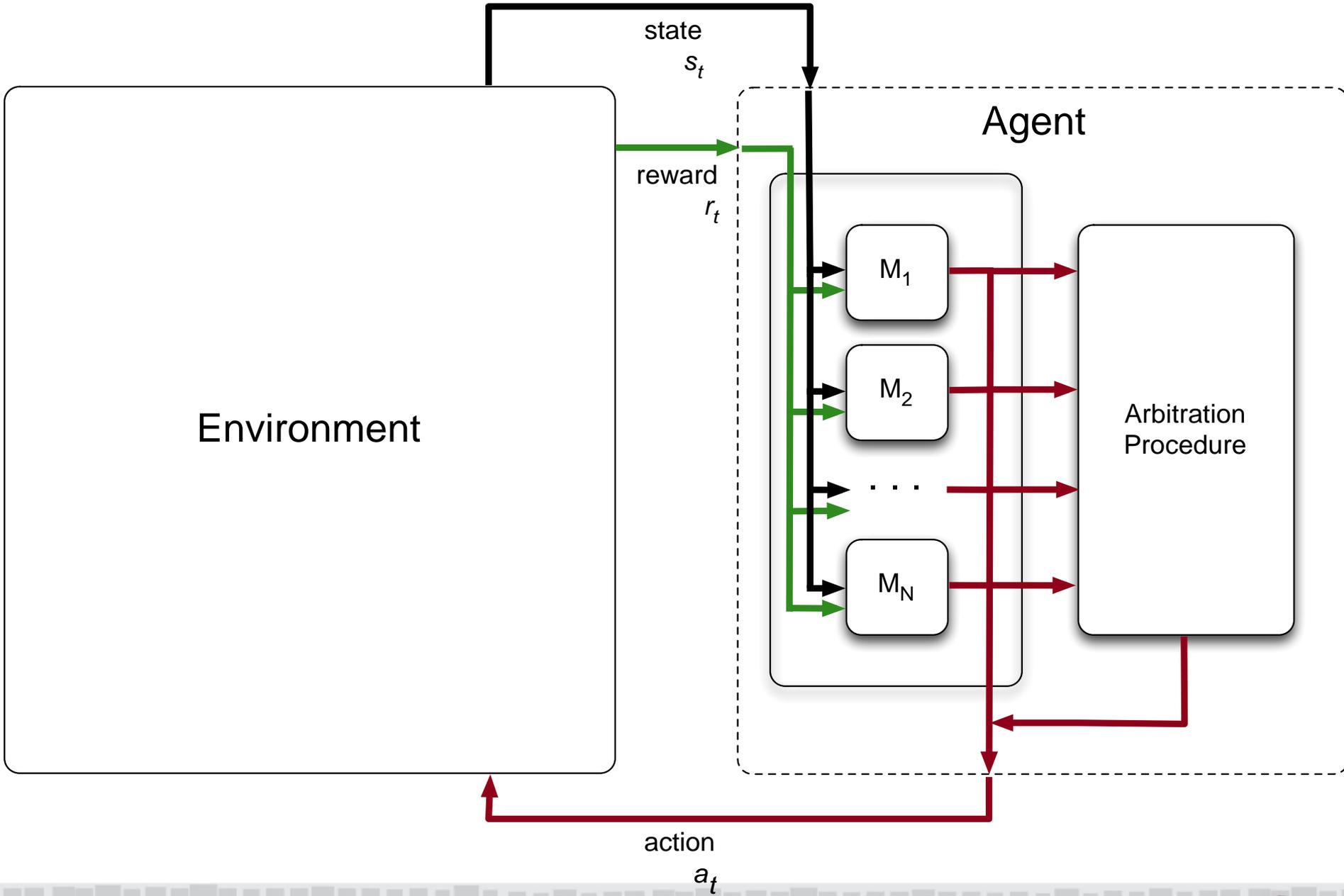
# Reinforcement Learning

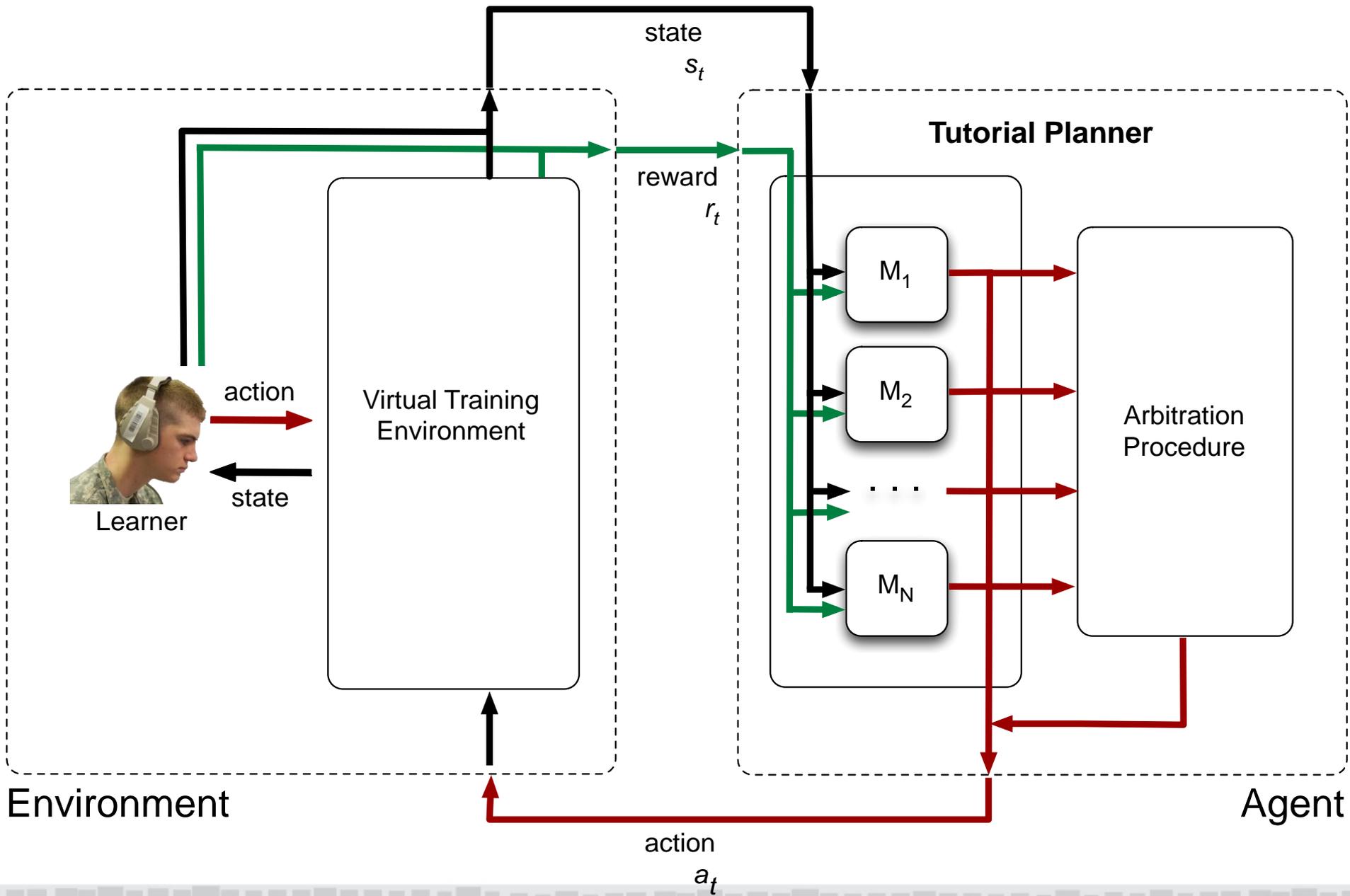
- **Problem:** Devise software agent that learns how to behave in order to maximize numerical reward
- No external supervision
- Delayed rewards

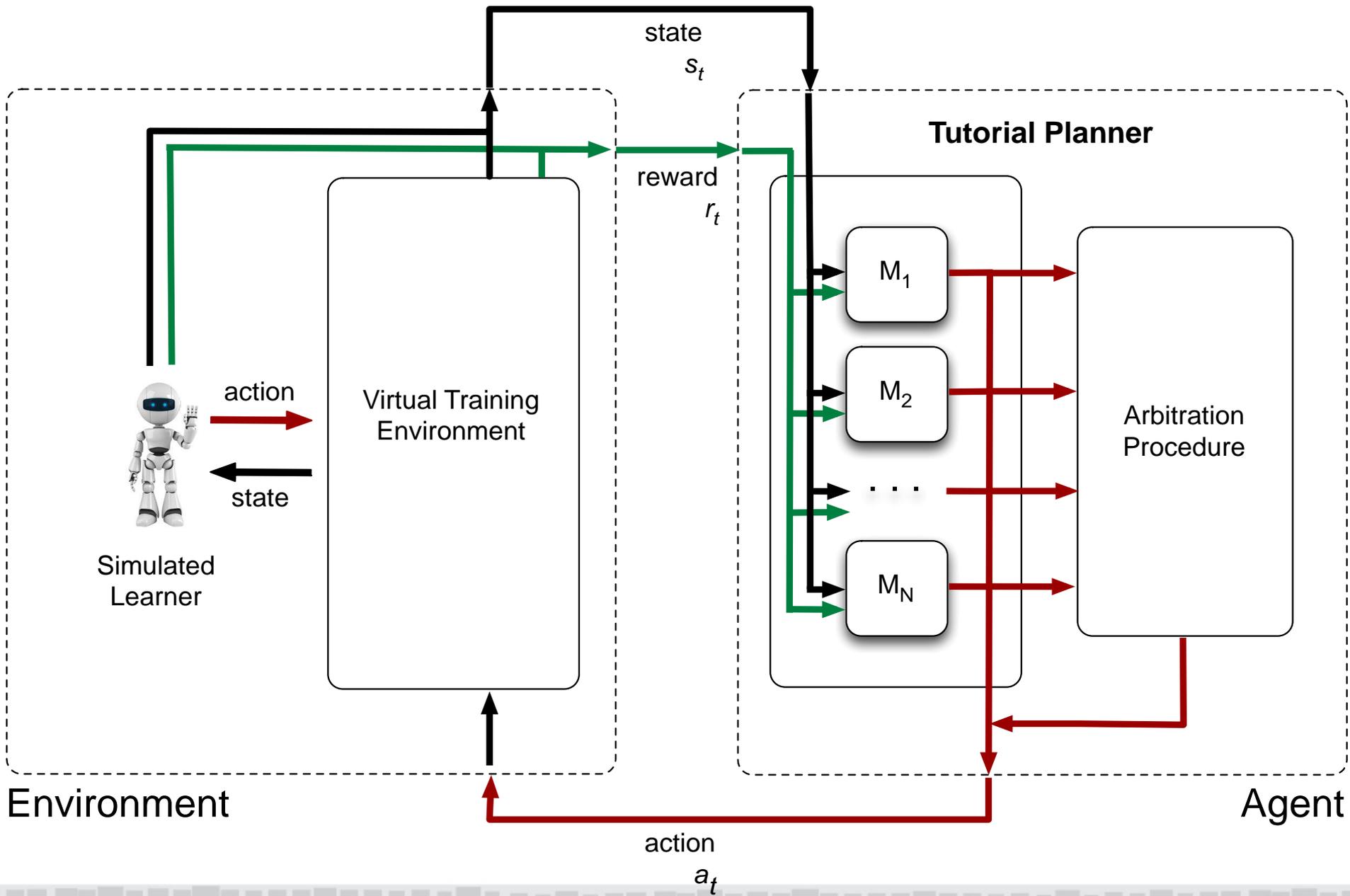


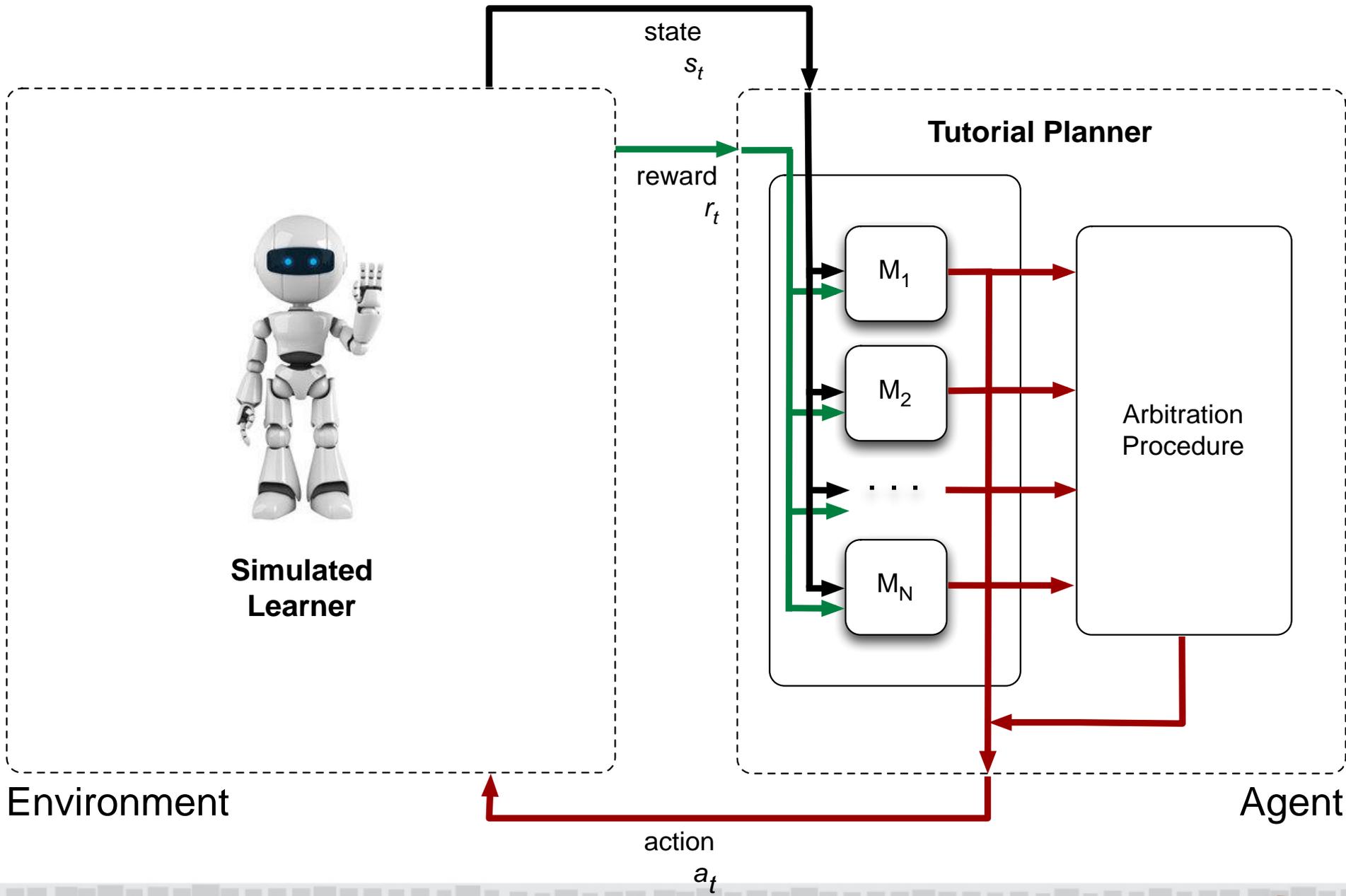
Adapted from Sutton & Barto (1998)











# Markov Decision Processes



- Reinforcement learning problems are often modeled as Markov decision processes (MDP)
  
- Defined by a tuple  $\mathcal{M} = (\mathcal{S}, \mathcal{A}, \mathcal{P}, \mathcal{R})$ 
  - Environment state set  $\mathcal{S}$
  - Action set  $\mathcal{A}$
  - State transition model  $\mathcal{P}: \{\mathcal{S} \times \mathcal{A} \times \mathcal{S}\} \rightarrow [0, 1]$
  - Reward model  $\mathcal{R}: \{\mathcal{S} \times \mathcal{A} \times \mathcal{S}\} \rightarrow \mathbb{R}$
  
- Solution is optimal policy  $\pi^*: \{\mathcal{S}\} \rightarrow \mathcal{A}$

# Policy Learning



- Online learning
  - Interleave data collection and model operation
  - Temporal-difference methods
  - Works well with simulation-generated training data
  
- Offline learning
  - Separate data collection and model operation
  - Certainty equivalent learning (Kaelbling, Littman & Moore 1996)
  - Approximate state-transition model and reward model using collected corpus

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# Simulated Students Overview



## Definition:

“... computer systems that simulate human students as they learn educationally significant subject matter ... ”

(VanLehn, Ohlsson, & Nason, 1993)

## Applications

1. Provide teachers with practice opportunities
2. Serve as co-learners for human students
3. Conduct formative evaluations of learning materials

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4. Enable ITS authoring systems using authoring-by-tutoring  
(Matsuda, Cohen, & Koedinger, 2014)
5. Generate synthetic data for training data-driven intelligent tutors  
(Beck, Woolf, & Beal, 2000; Wang et al., 2017)

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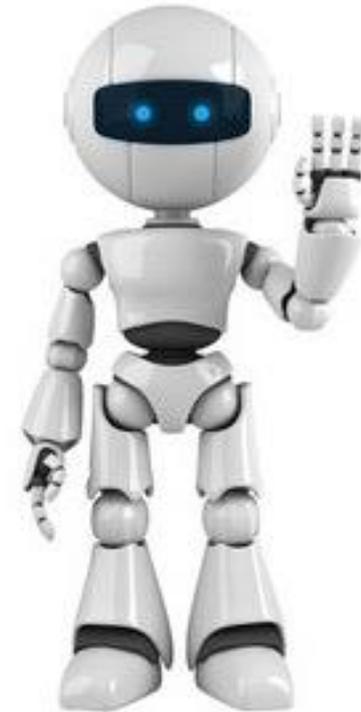
# Related Work



- **AIED Workshop Series on Simulated Learners**  
(AIED-2013, AIED-2015)
- **SimStudent** (Matsuda, Cohen, & Koedinger, 2014)
- **Simulated students in RL-based tutoring systems**  
(Beck, Woolf, & Beal, 2000; Folsom-Kovarik, Sukthankar, & Schatz, 2013; Wang et al., 2017)
- **Simulated users in spoken dialogue systems** (Schatzmann, Weilhammer, & Young, 2006; Young et al., 2013)

# Design Dimensions for Simulated Students

- Representational Granularity
- Computational Framework
- Model Complexity
- Learning Process
- Model Validity



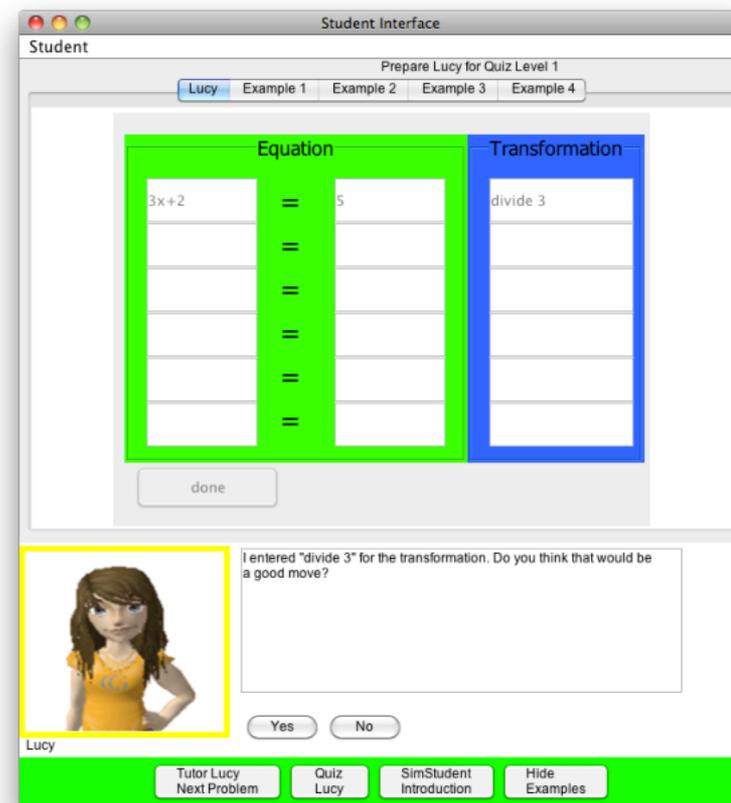
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# Representational Granularity

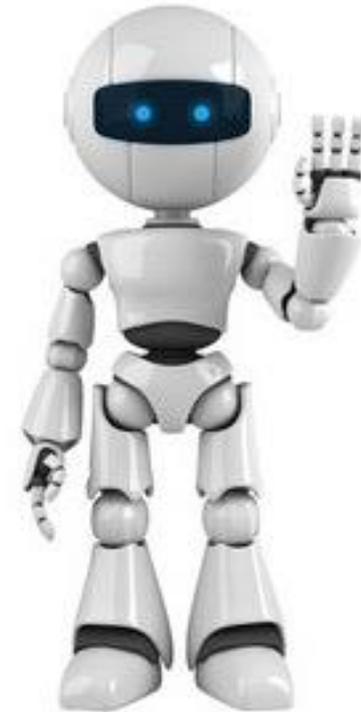
- Varying levels of temporal granularity
- Fine-grained representation  
SimStudent (Matsuda, Cohen, & Koedinger, 2014)
- Coarse-grained representation  
SimGrad (LeLei & McCalla, 2015)



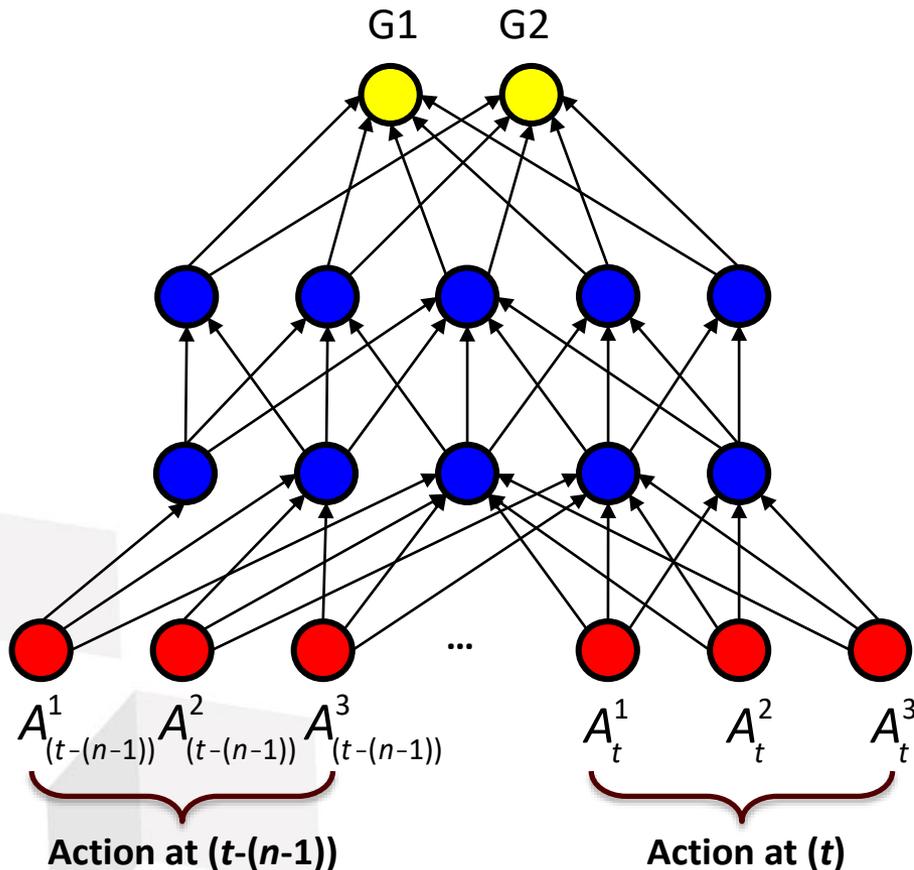
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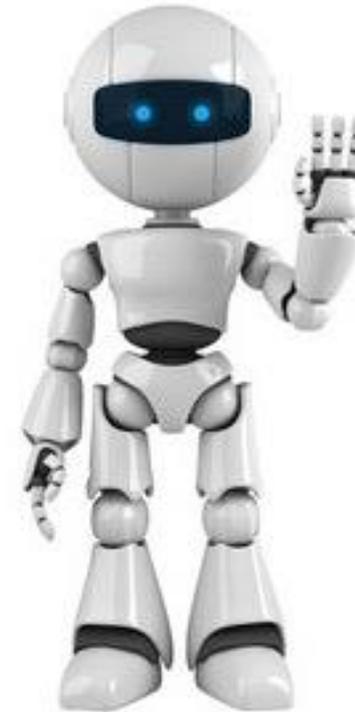
# Computational Framework



- Expert systems
- Closed-form expressions
  - Weighted sum (Frost & McCalla, 2015)
  - Item response theory (Hernando, Guzman, & Conejo, 2013)
- Machine learned models
  - Linear regression (Beck, Woolf, & Beal, 2000)
  - Hidden Markov models (Pardos & Yudelson, 2013)
  - LSTM neural networks (Wang et al., 2017)

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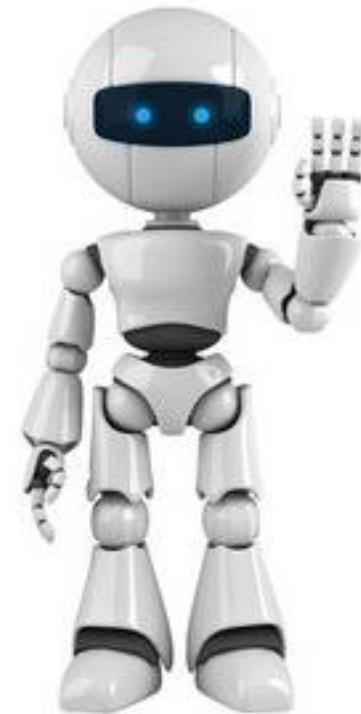
# Model Complexity



- Number of parameters
- Linear vs non-linear functions
- Tabular vs algorithmic simulations (VanLehn, Ohlsson, & Nason, 1993)
  - Tabular models are efficient and easily authored
  - Algorithmic models generalize to novel situations
- Run-time efficiency

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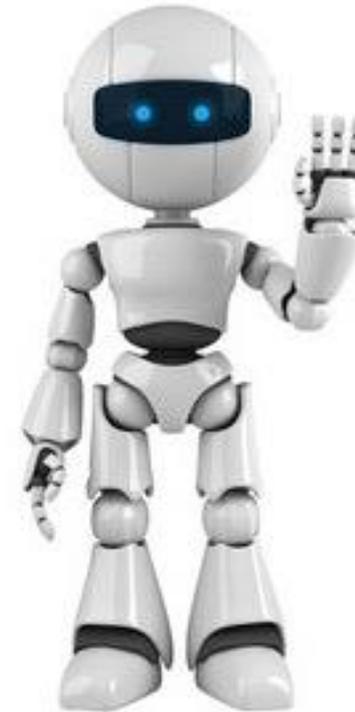
# Learning Process

- Cognitive simulations
  - Problem-solving behavior (Matsuda, Cohen, & Koedinger, 2014)
  - Academic performance (LeLei & McCalla, 2015)
- Affective simulations
  - Emotion regulation (Sabourin et al., 2013)
- Social simulations
  - Peer-to-peer learning (Frost & McCalla, 2013)



# Design Dimensions for Simulated Students

- Representational Granularity
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- **Model Validity**



# Model Validity



- Not all simulated students are validated
  - Designer intuition
  - Theoretically grounded
  - Empirically derived
- Designer bias
- Population-dependent aspects of learning are difficult to estimate

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# Tutorial Planning for Counterinsurgency Training



## Adaptive Hypermedia



UrbanSim Primer

## Simulation-Based Training



UrbanSim  
(McAlinden, Pynadath, & Hill, 2014)

# COIN Training Testbed

## UrbanSim Primer



The screenshot displays the 'UrbanSim Primer' interface. At the top, there is a navigation bar with tabs for Lesson 1 through Lesson 6. Below this, a video player shows a man in a military uniform, identified as LTC (Ret.) John A. Nagl. To the left of the video, there is a sidebar with a bio for LTC Nagl, including a small portrait and text describing his military service and education. Below the video, there is a caption: 'LTC (Ret.) John A. Nagl Co-author "Counterinsurgency Field Manual" FM 3-24'. At the bottom of the interface, there is a progress indicator showing '0 out of 8 completed' and a set of icons for different topics: COIN, Managing Info, and IIR Legitimacy.

- Adaptive hypermedia learning environment
- Range of doctrinal concepts of COIN
  - Population support
  - Clear-Hold-Build
  - Intelligence gathering
- Preliminary instruction on UrbanSim usage

# COIN Training Testbed



## UrbanSim

- Simulation-based learning environment
- **Role:** Learner is battalion commander
- **Objective:** Maximize civilian support for host nation government
- PsychSim social simulation engine

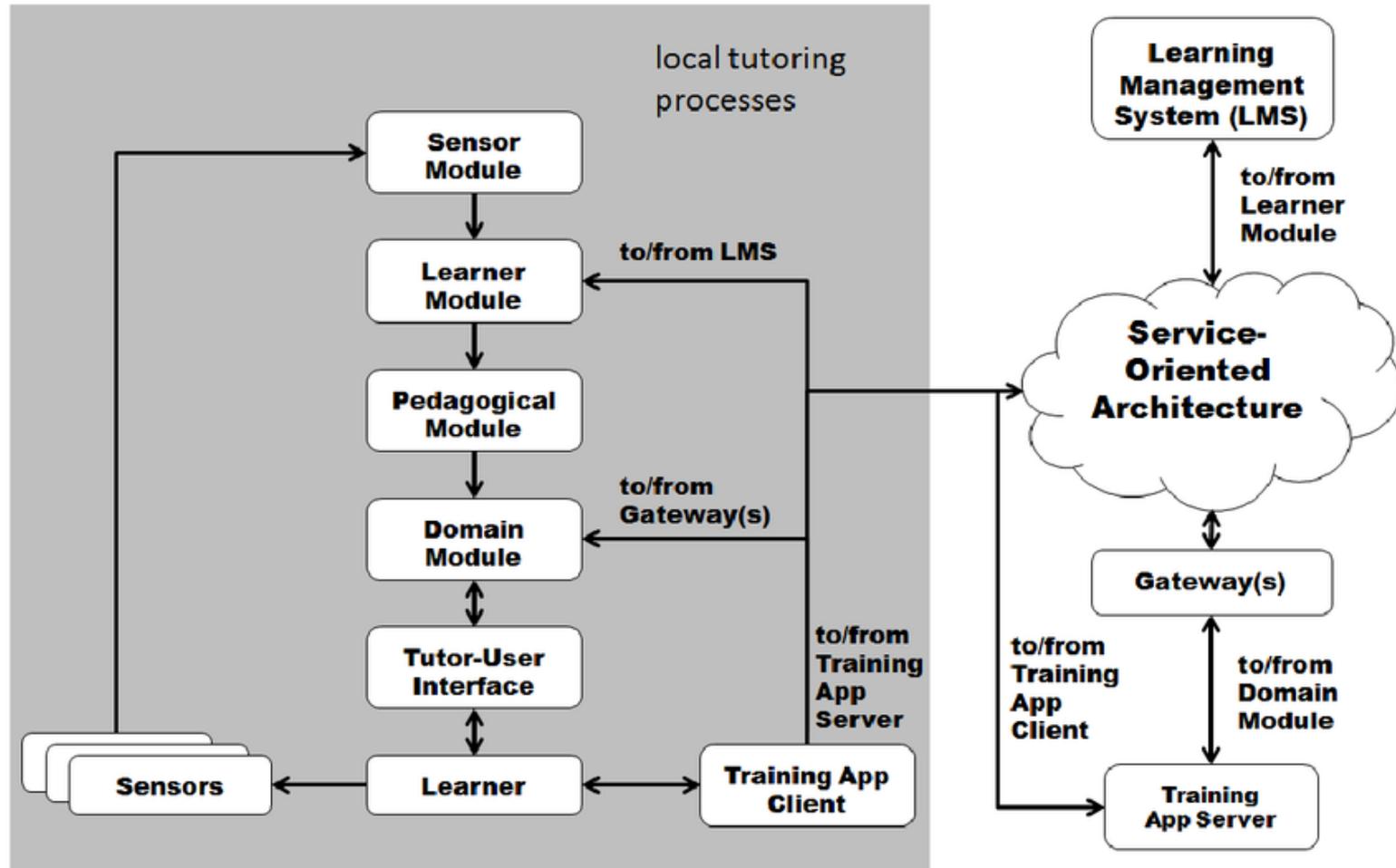


# Generalized Instructional Strategies for COIN Training

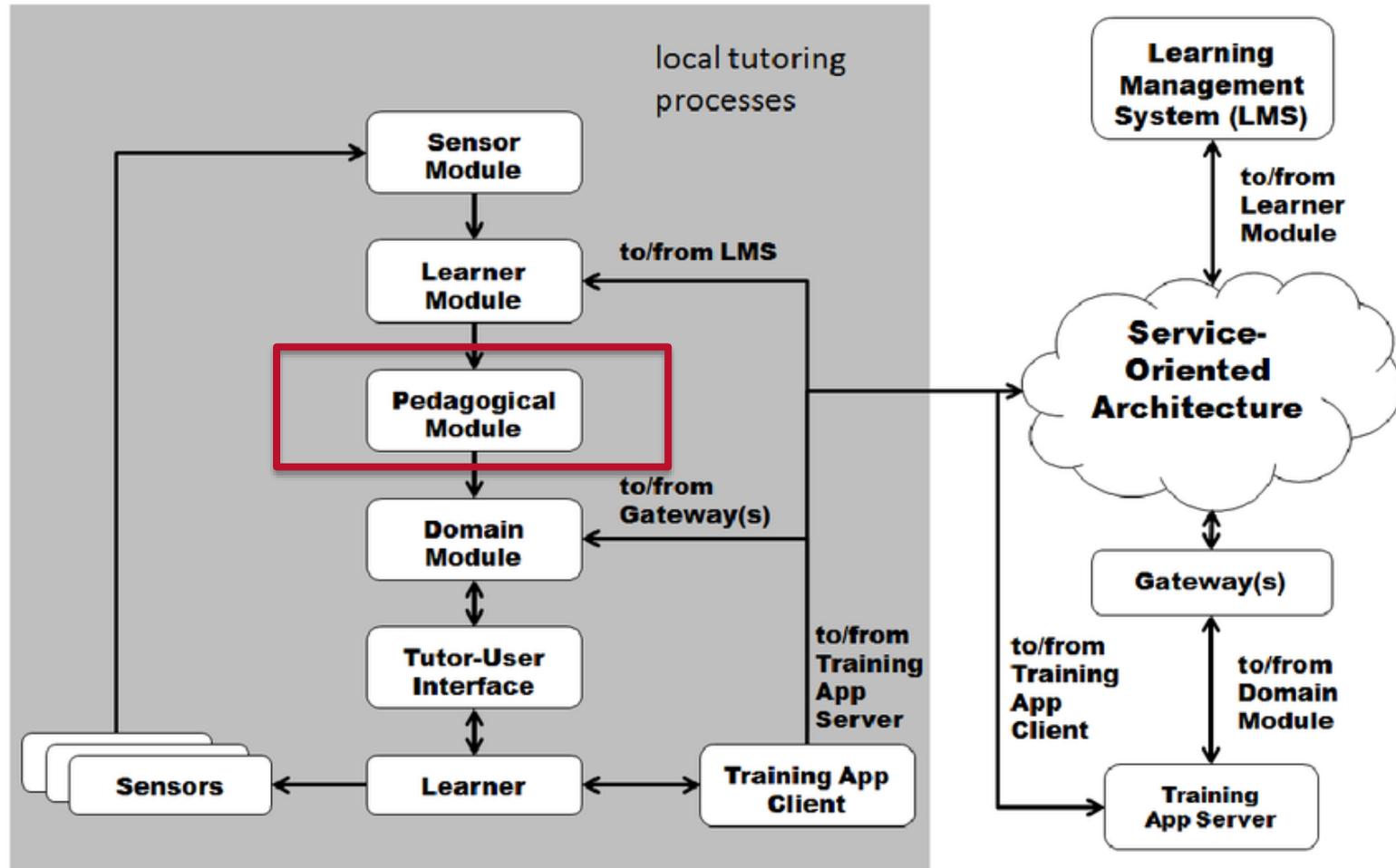


- High-level instructional strategies
  - Single-topic coaching
  - Multi-concept review
  - Feedback on unproductive learning behaviors
  
- ICAP-inspired implementation strategies (Chi, 2009)
  - Constructive
  - Active
  - Passive

# GIFT Pedagogical Module



# GIFT Pedagogical Module



# Toward Simulated Students for COIN Training



- *Bipartite model* of simulated students
  - Student behavior
  - Learning outcomes
- Tabular joint probability distribution
  - Values estimated from pilot study data
  - Data sparsity challenges
- Granularity
  - *UrbanSim Primer*: One lesson
  - *UrbanSim*: One turn of simulation

# Toward Simulated Students for COIN Training



- Devise simulated student for each MDP
- Domain-independent state features
  - Student knowledge & traits
  - Task states
  - Pedagogical history
- Model student responses to pedagogical actions
- Rewards model student learning gains
- Population of simulated students

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# Conclusions



- Simulated students show promise for generating synthetic data to train data-driven tutorial planners
- Design of simulated students presents several questions:
  - Representational granularity
  - Computational framework
  - Model complexity
  - Target learning process
  - Model validity
- We are devising simulated students to support RL-based tutorial planning for COIN training in GIFT

# Future Directions



- Conduct studies validating simulated students by comparing synthetic data with human student data
- Devise tools and workflows for incorporating tutorial planning policies induced from simulated students in GIFT
- Provide tools for non-expert users to work with simulated students, including creating, configuring, sharing, and refining simulated student models
- Conduct GIFT studies with Mechanical Turk populations to complement synthetic data from simulated students

# Acknowledgments



- NCSU Army ROTC Program
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